



SOLEIL II PROJECT

- SOLEIL II MAIN PARAMETRES
- SOLEIL II BPM SPECIFICATIONS
- BPM SIMULATION
 - BEAM PROFILE AND POWER SIMULATIONS
 - THERMAL SIMULATIONS
- BUTTON PROTOTYPE TEST
 - CURRENT MACHINE INSTALLATION SETUP
 - MEASUREMENTS WITH BEAM
- CONCLUSIONS AND PERSPECTIVES





SOLEIL II Storage Ring Key Parameters

- Non-standard MBA lattice: 12 x 7BA + 8 x 4BA / 2.75 GeV / 354 m / 500 mA
- 2. ~83 pm.rad (~53 pm.rad round beam as ultimate goal).
- 3. 22 straight sections (7 different lengths).
- 4. NEG coated very small vacuum chamber diameter (12 mm)
- 5. Extensive use of permanent magnets (all dipoles, RB and main quadrupoles).
- Miniaturization.
- 8. Off-axis injection with Multipole Injection Kicker (MIK).
- 9. Energy savings and reduced energy footprint.

Parameters	SOLEIL	SOLEIL II
Energy [GeV]	2.75	2.75
Circumference [m]	354.10	353.97
Maximum Beam Current [mA]	500	500
Lattice Type	DBA	7BA-4BA
Cell Number	24	20
Natural Emittance [pm.rad] Round beam (100% coupling)	3 900	83 53
Energy Spread	1.02 E-3	0.91 E-3
Natural RMS Bunch Length [ps]	16.1	8.6
Transverse Damping Times, τx/τy/τs [ms]	6.9 / 6.9 / 3.5	7.8 / 14.3/ 12.4
Momentum Compaction Factor	4.2 E-4	1.06 E-4
Energy Loss per Turn [keV]	917	453
Overall RF Voltage [MV]	2.6	1.8
RF Frequency [MHz]	352.20	352.33
RF Power into the Beam [kW]	575	245
Synchrotron Frequency [kHz]	4.2	1.8

Parameters without insertion devices nor harmonic cavity





SOLEIL II BPM SPECIFICATIONS

Beam Position Monitor main requirements

- •High Resolution at nominal operating conditions
- •High S/N Ratio at low current for optimal resolution during first turns
- •Long-Term Stability to ensure operation for users

Туре	Data	Spec.	Conditions
	Fast acquisition (~100 kHz, DC-2kHz bandwidth)	100 nm rms	Nominal current / Nominal filling pattern (500 mA / 416 bunches)
Resolution	Turn by Turn	1 μm rms	
	Turn by Turn	100 µm rms	
	Slow Acquisition (~10 Hz)	1 μm rms	0.1-1 mA in 1 quarter (commissioning)
Beam Current Dependence	-	10 μm	From 0.1 mA – to nominal current
Absolute		< 500 µm	Before BBA
accuracy		< 5 µm	After BBA
Long term		500 nm	Day drift
Stability		1 µm	Week drift





SOLEIL II BPM Types

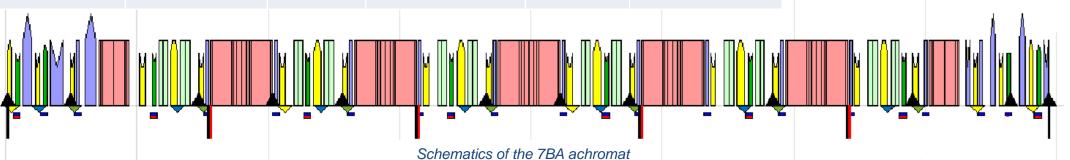
A large number of BPM types:

SOLEIL II BPMs	Location	Nb. of units	Chamber inner diameter	Button diameter	Fixation
BPM16	Arcs	128	16 mm	16 mm 6 mm Girder	Girder
	Arcs, behind BM source points	l source		Welded on dipole vacuum chamber	
BPM20	Standard straight and SD01L/SD11L matching sections	40	20 mm	7 mm	Ground (SS) or girder (matching)
BPM24	Long straight sections	12	24 mm	7 mm	Ground

Design Features for Maximum Stability

Enlarged tapered sections for BPMs within SR shadow

- •Rigid mechanical supports minimize displacement due to temperature fluctuations
- to Bellows reduce vacuum chamber constraints

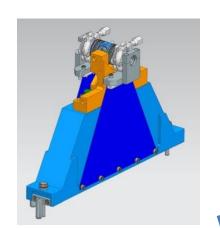




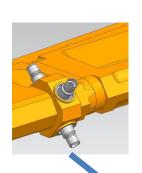


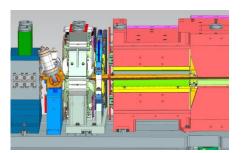
BPM Mechanical Implantation

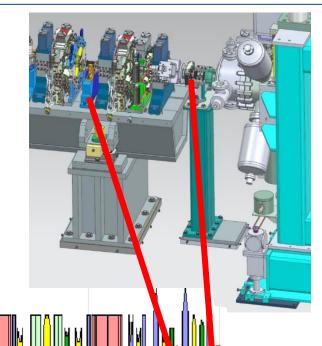
Standard arc BPM16 (x128):

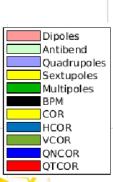


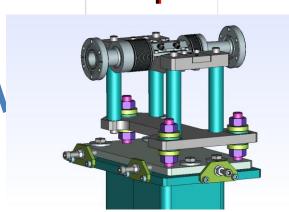
Integrated arc BPM16 (x16): **Welded** on the dipole vacuum chamber

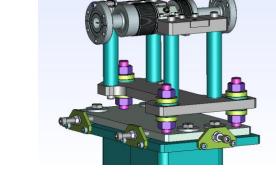










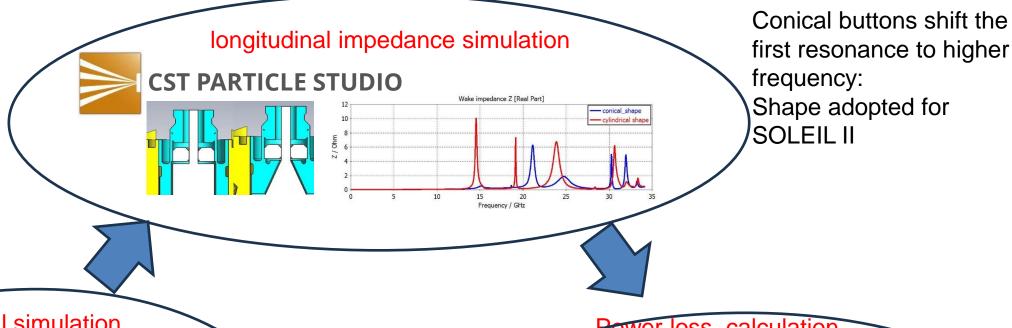


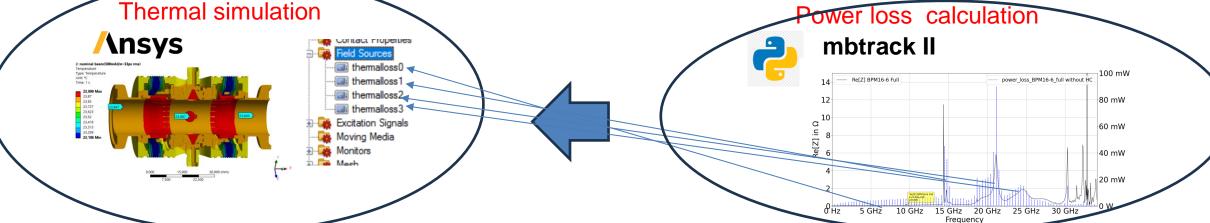
Standard straight section BPM20 (x40)





SIMULATION WORKFLOW





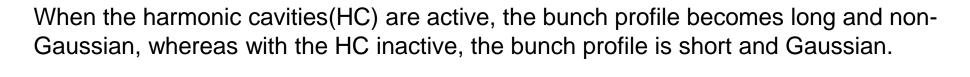
Importing CST field maps into ANSYS thermal solver with the appropriate coefficients allows for calculating the total heating and the contribution of each resonance

MBTrackII models power loss by simulating beam interactions with longitudinal impedance



Filling patterns for SOLEIL II

	Uniform mode with HC	32 bunches mode	Degraded uniform mode without HC	
Current(mA)	500	200	300	
Nombre of bunches	416	32	416	
Bunch length (ps rms)	53	55-60	10	
Bunch profile	No gaussian Equilibrium bunch profile 25 28 30 30 30 100 50 100 100 100 10	No gaussian Equiniprium durich promie	Gaussian Pulse: 10 ps RMS Gaussian Pulse: 10 ps RMS 20 40 40 40 40 40 40 40 40 40	







Effect of bunch longitudinal profile

 $\Delta P = (f_0 e N_{beam})^2 \sum_{p=+\infty}^{p=+\infty} |\Lambda(p\omega_0)|^2 Re[Z_{\parallel}(p\omega_0)]$

in the case of a constant impedance as RESISTIVE WALL:

Example of RW for beam pipe 7cm length and diameter = 16mm equivalent to BPM16 size.

The non-Gaussian beam delivers the same amount of power as a Gaussian beam that's 15% shorter.

by courtesy of Alexis Gamelin

Distribution	Real profile	Equivalent Gaussian	Equivalent Gaussian of reduced size 15 %
Lenght RMS	53 ps	53 ps	45 ps
Bunch Profile	Equilibrium bunch profile 23 - 20 - 130 - 100 - 50 0 50 100 150 200 12 - 200 - 130 - 100 - 50 0 50 100 150 200	1e9 7 6 5 4 3 -200 -150 -100 -50 0 50 100 150 200	1e9 8 - 2 - 200 -150 -100 -50 0 50 100 150 200 T [ps]
Impedance and beam Spectrum	3.18	0 16 0 25 0 25 0 25 0 25 0 25 0 25 0 25 0 2	015 017 018 019 019 029 029 020 020 020 020 020 020 020 02
Spectral power distribution	0.14 power loss real gratite 0.12 c	2.16 pre-irrorelance pre-irror	012 princedurce prose (sa, Gaussin explit less 15%) 35 mm 012 3 mm 013 2.5 mm 014 7 min cellurce prose (sa, Gaussin explit less 15%) 15 mm 015 2.5 mm 016 2.5 mm 017 018 1
Power dissipation	77 mW	62 mW	80 mW



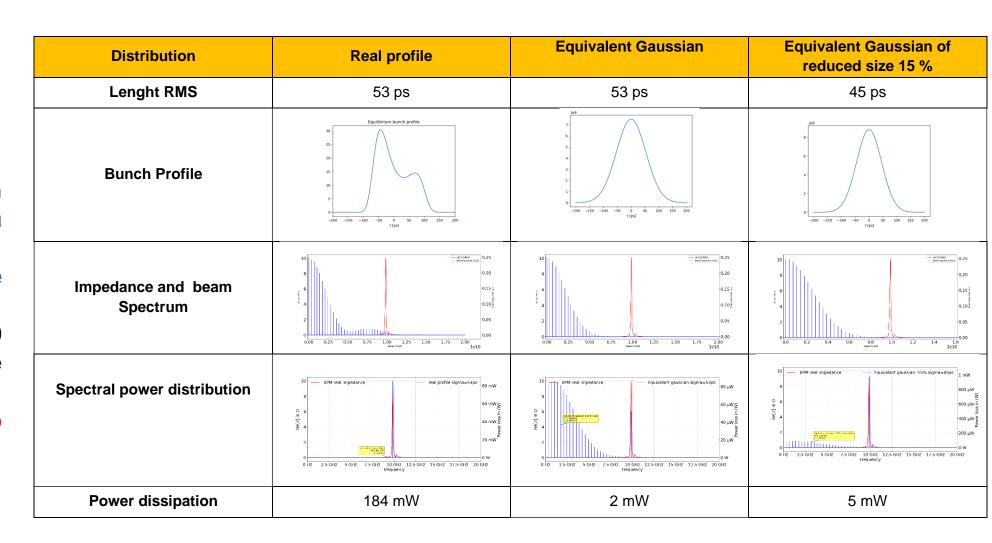
Case of impedance with resonance pick



The previous assumption is not applicable for a non-constant impedance, like in the case of trap modes.

Resonances in the 5 to 20 GHz range must be considered seriously.

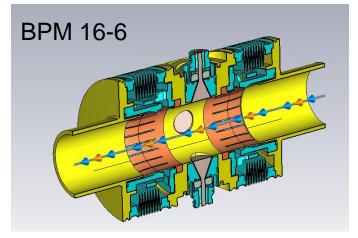
Exemple : BPM with trap modes @10GHz and 10Ω

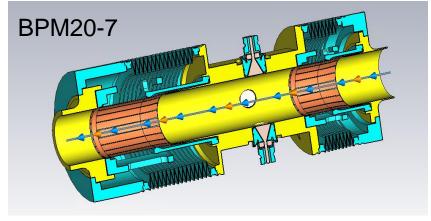


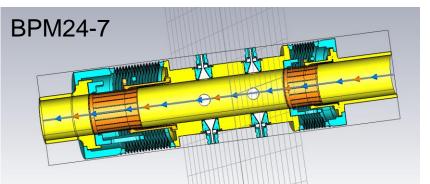


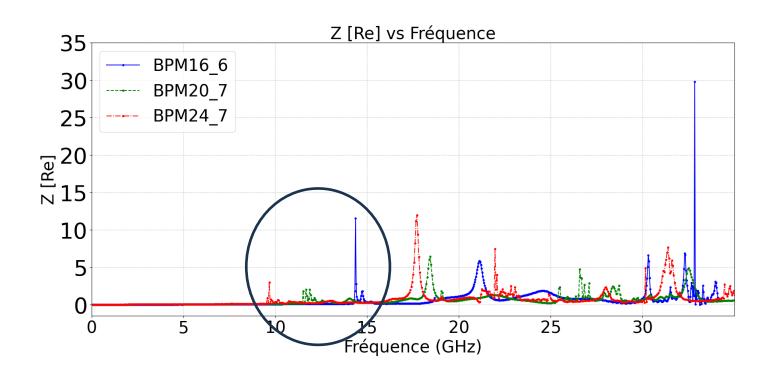


Electromagnetic Simulations









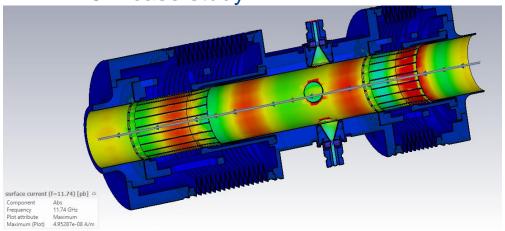
Resonance between 10 GHz and 15 GHz

- Simulation of full BPM block
- Were not present simulating the BPM section only

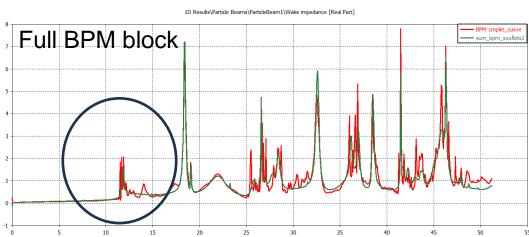


Investigation of the first resonance

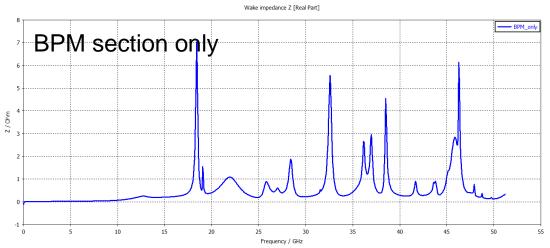
BPM20-7 case study:



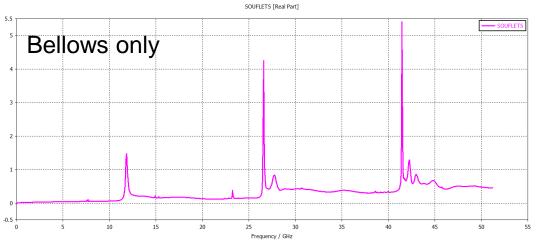
A field monitor positioned at these frequencies indicates power deposition at the bellows (surface current visualization).



Long. impedance of the full BPM block (red) compared with the sum of independent simulation of BPM section and bellows (green).



Long. impedance of the BPM section



Long. impedance of the bellow.



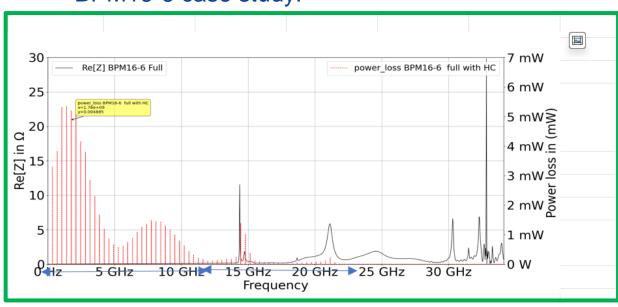


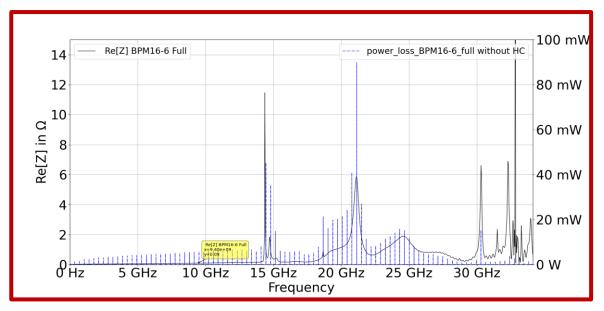
Total Power Loss

- Resulting power loss on the complete BPM blocks:
 - Very limited (max 0,21 W) in the nominal operational mode
 - Stronger (up to 2,4 W) in case we should operate without HC (degraded mode)

Power loss (W)	BPM16	BPM20	BPM24
Nominal w. HC (σ=53ps)	0.14	0.21	0.21
Degraded mode w/o. HC (σ=10ps)	1.6	2	2.4

BPM16-6 case study:





Power loss distribution in nominal mode

Power loss distribution in degraded mode

- Very small contribution from the bellows in nominal mode
- Stronger interaction with the beam in degraded mode coming both from the bellows but also from the first trap mode around the buttons.

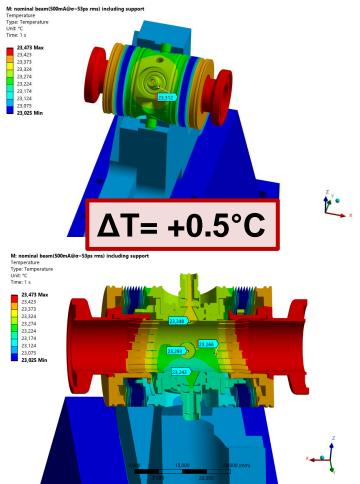




Thermal simulations

• BPM16-6:

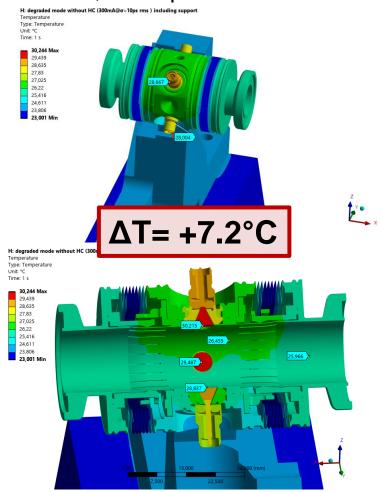
Nominal operational mode: 500mA, $\sigma=53$ ps with HC.



Natural convection coefficient=10 W/m²-K / ambient temperature = 23°C

BPM support equipped with a forced water-cooling system

Degraded operational mode: 300 mA, $\sigma=10 \text{ ps}$ without HC

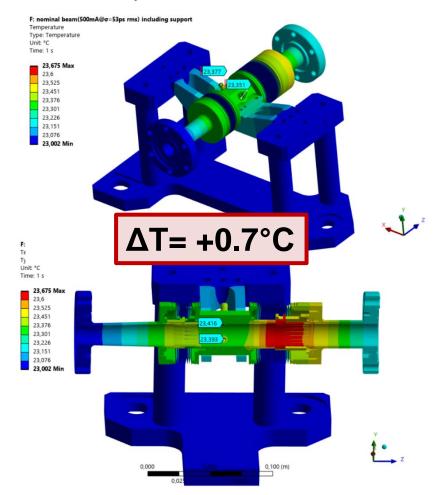




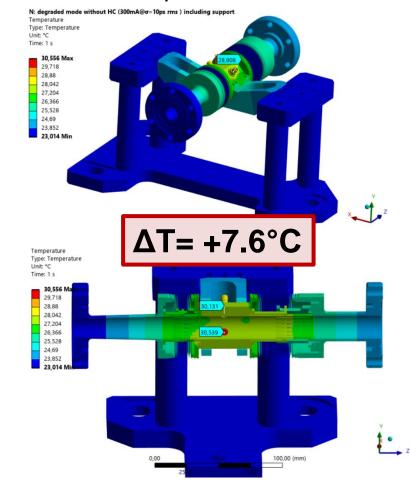


BPM20-7:

Nominal operational mode: 500mA, σ =53 ps with HC.



Degraded operational mode: 300 mA, σ =10 ps without HC



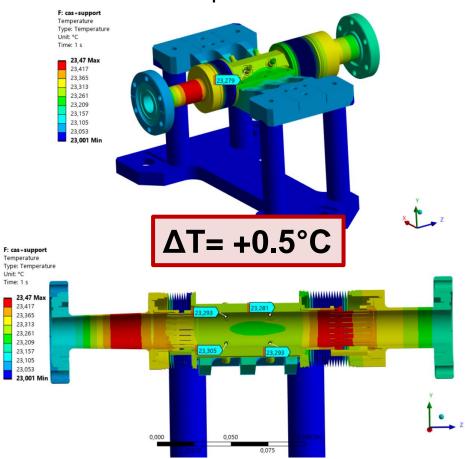




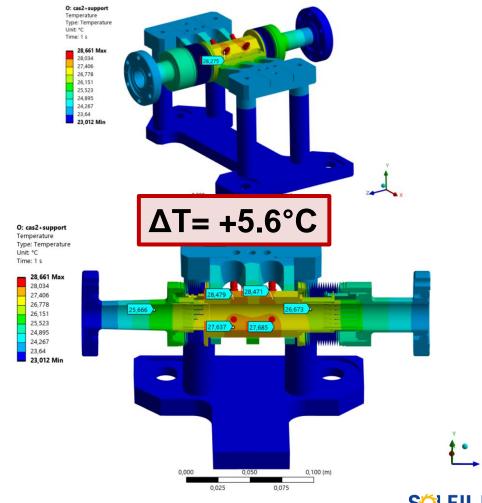
Thermal simulations

BPM24-7:

Nominal operational mode: 500mA with σ =53 ps with HC.

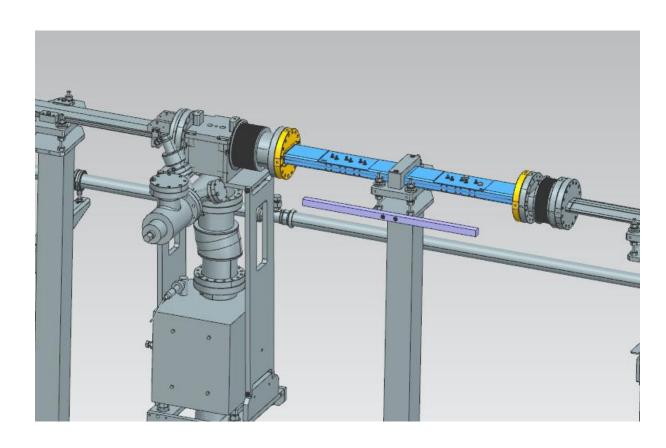


Degraded operational mode: 300 mA, σ =10 ps without HC



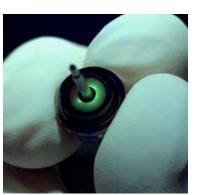


Buttons test on the current machine

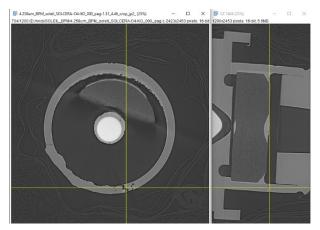


For more details, please refer to Nicolas Hubert presentation during the BPM workshop at ALBA https://indico.cells.es/event/1542/contributions/2943/ Installation of two sets of 12 feedthroughs supplied by two different manufacturers

One batch was withdrawn after leakage problems during the soldering and bake-out phase



Fluorescent oil shows transversal (top) or radial (bottom) cracks



CT scan by ESRF BM18. Crack is visible on the upper part (in-air) of Manufacturer 2.

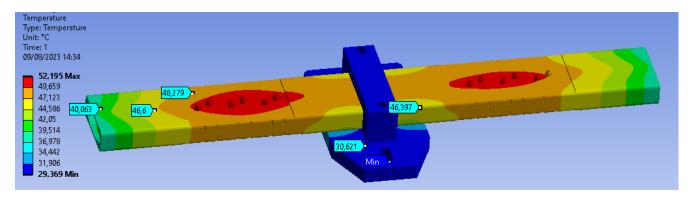




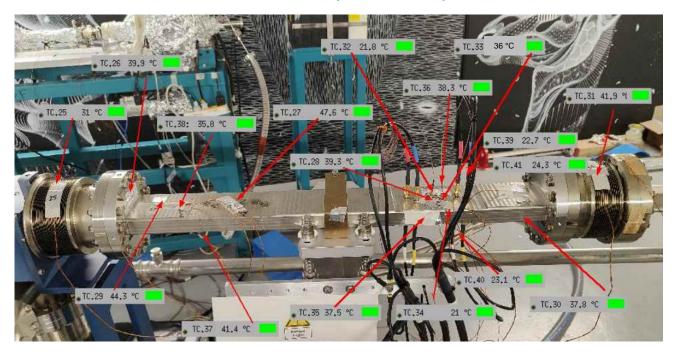
Button prototypes: beam tests

Temperature measurements:

- Sensors distributed on the VC body and on some feedthrough pins.
- Measurements in good agreement with simulations!
 - Observed temperatures are ~15% lower than expected.
 - Probably due to an overestimation of heat exchange with environment in simulations



Thermal simulation. Maximum expected temperature @ 500 mA is 52 °C



Maximum measured temperature @ 500 mA is 47.6 °C



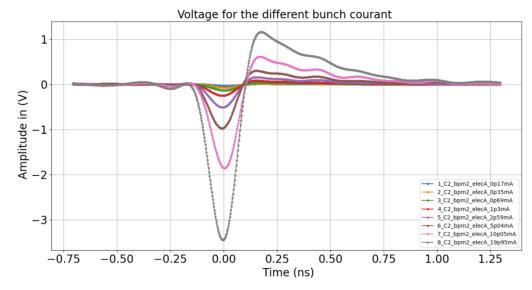


Collected signal:

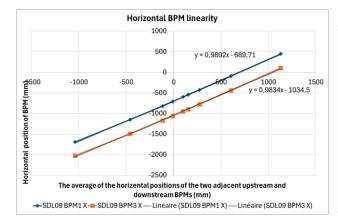
- Measurement conditions:
 - Scope: 4GHz BW
 - 32-meter cable (4dB attenuation at 352 MHz)
 - Additional 15 dB attenuator
- Collected signal at 500 mA is -5 dBm
 - In good agreement with analytical calculation (expected -7 dBm)
- Long term monitoring does not show any glitches that could be a sign of multipactor.
 - Observed temperatures are ~15% lower than expected.
 - Probably due to an overestimation of heat exchange with environment in simulations

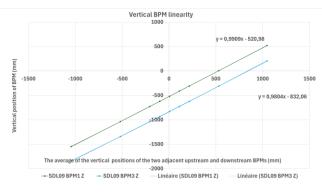
SOLEIL II BPM button conical design is validated by the beam tests.

Button prototypes: beam tests



Oscilloscope pulse amplitude acquisition vs. bunch current





DEELS 2025 19

BPM response vs beam position in horizontal plane (left) and vertical plane (right).

Conclusion



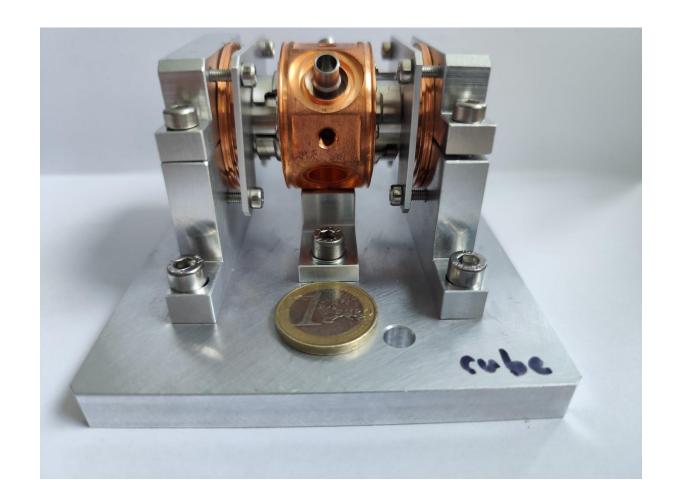
- BPM simulations are almost terminated.
- Thermal simulations give acceptable temperature increase (+0.5°C in nominal operational mode).
- Thermal measurements on the chamber confirm that the simulation methodology is accurate.
 - Buttons have been positioned 8 mm from the beam, which matches the SOLEIL II BPM16.
 - Collected signal is compliant with theoretical calculation.
 - Button temperature does not exceed 40 °C, which is below the simulation predictions

Next steps:

- Manufacturing of two 6 mm button batches after design modifications (better robustness to bake-out expected)
 - Validation of laser welding on CuCrZr (for BPMs integrated on bending magnet VC)
 - Conduct bake-out tests to validate ceramic robustness





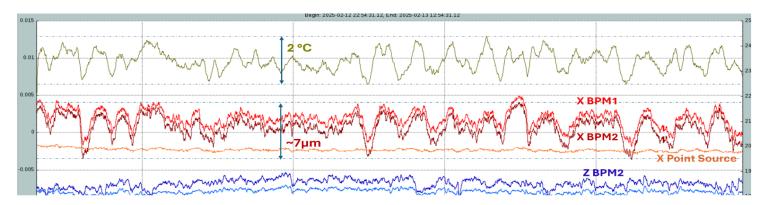


THANK YOU FOR YOUR ATTENTION





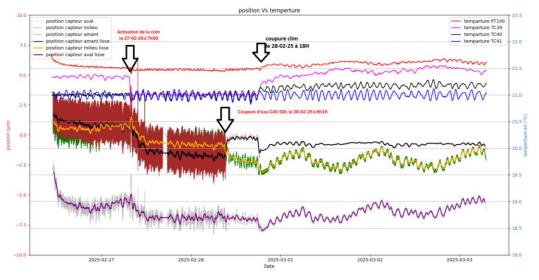
Setup stabilities



Displacements observed in the H plane are correlated with significant temperature variations in the area (around 2°C).



Investigation during technical shutdown: installation of three position sensor



"A combination of two disturbances is observed: a slow variation due to temperature changes, and a fast one linked to the cooling system of the vacuum chamber."

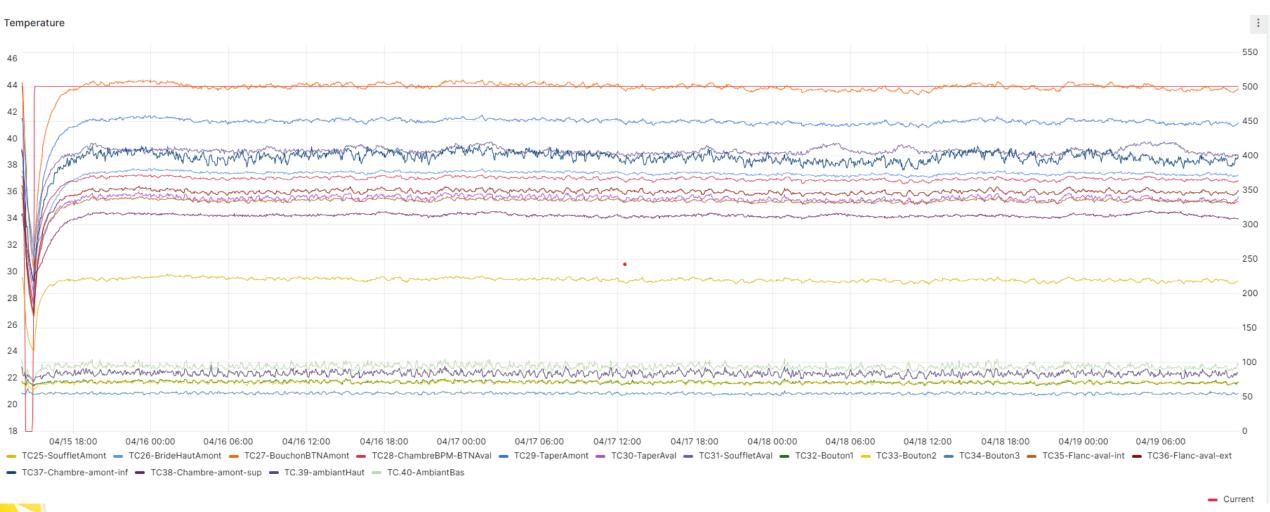
Installation of a second supplementary support to eliminate disturbance







Temperature stability







Position stability

